

# **MODEL QUESTION PAPER**

**MFE3**

## **I Semester M.TECH Examination, August 2011 CONTROL THEORY**

Time: 3 Hours

Max. Marks: 75

### **GROUP A : Answer any three questions.**

- Q.1 Distinguish between open loop and closed loop system.
- Q.2 Explain following terms -(a) Sensitivity (b) stability (c) Steady state error.
- Q.3 Show with the help of examples that introduction of derivative mode of control in a feedback system with proportional control makes the system response less oscillatory. What is its effect on steady state accuracy?
- Q.4 What is PI controller? Write its input output transfer function.
- Q.5 What is transfer function of a system? Deduce the expression for transfer function a typical closed system.

### **GROUP B : Answer any three questions.**

- Q.6 What is the advantage of Bode plot over Nyquist plot?
- Q.7 For the following characteristic equation of linear control system, construct the root loci for  $K \geq 0$ . Determine the marginal value of  $K$  for stability.  $Z^2 + (0.15K - 1)Z + 0.5 = 0$
- Q.8 Discuss various components of Control System. What is PID control? Explain the principles of working of an electronic PID controller with a suitable diagram.
- Q.9 State the stability by applying Routh-Hertwitz criteria.  
 $4s^4 + s^3 + 6s^2 + 3s^2 + 11s + 6 = 0$
- Q.10 A unity feedback control system having O.L.T.F. is given below. Draw the Bode Plot. Determine the values of G.M., P.M.,  $\omega_{gc}$  &  $\omega_{pc}$ . Comment on Stability.

### **GROUP C: All Questions are Compulsory.**

#### **Q.11 Fill in the blanks**

- (i) A unity feedback system has an open loop transfer function  $G(s) = 25/s(s+8)$ , then damping ratio is \_\_\_\_\_.
- (ii) The transfer function is the ratio of \_\_\_\_\_.
- (iii) The multiplying factor  $\frac{1}{|OA|}$  is the \_\_\_\_\_ margin.
- (iv) Lead network \_\_\_\_\_ the bandwidth of the system.
- (v) For every bounded input the output is bounded is referred as \_\_\_\_\_

system.

**Q.12 Multiple choice question.**

- (i) In force current analogy mass is analogous to \_\_\_\_\_.
  - (a) Inductance
  - (b) Current
  - (c) Voltage
  - (d) Capacitance
- (ii) In a second order system, if the damping ratio  $\xi$  is less than unity, the system will be \_\_\_\_\_.
  - (a) Under damped system
  - (b) over damped system
  - (c) Critically damped system
  - (d) freely oscillation
- (iii) The initial slope of Bode Plot for a transfer function having simple pole at origin is \_\_\_\_\_.
  - (a) 20dB/decade
  - (b) -40 dB/decade
  - (c) 40 dB/decade
  - (d) -20dB/decade
- (iv) Phase cross over point is one at which Nyquist Plot intersect the \_\_\_\_\_.
  - (a) Positive real axis
  - (b) negative real axis
  - (c) Positive imaginary axis
  - (d) negative imaginary axis
- (v) From the Nichol's chart, one can determine the following quantities pertaining to a closed loop system \_\_\_\_\_.
  - (a) Magnitude and phase
  - (b) Bandwidth
  - (c) Magnitude only
  - (d) Phase only

**Q.13 True or false**

- (i) In mechanical system, the spring force is proportional to acceleration.
- (ii) The output of system is given by  $C(s) = 1/s^2(s-3)$   
The output will increase with respect to time
- (iii) Laplace transform of impulse function is one.
- (iv) The lag compensator decreases the bandwidth
- (v) The characteristic equation of an armature controlled d.c motor is of second order equation.

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